

BFS-based Symmetry Breaking Predicates for DFA Identification



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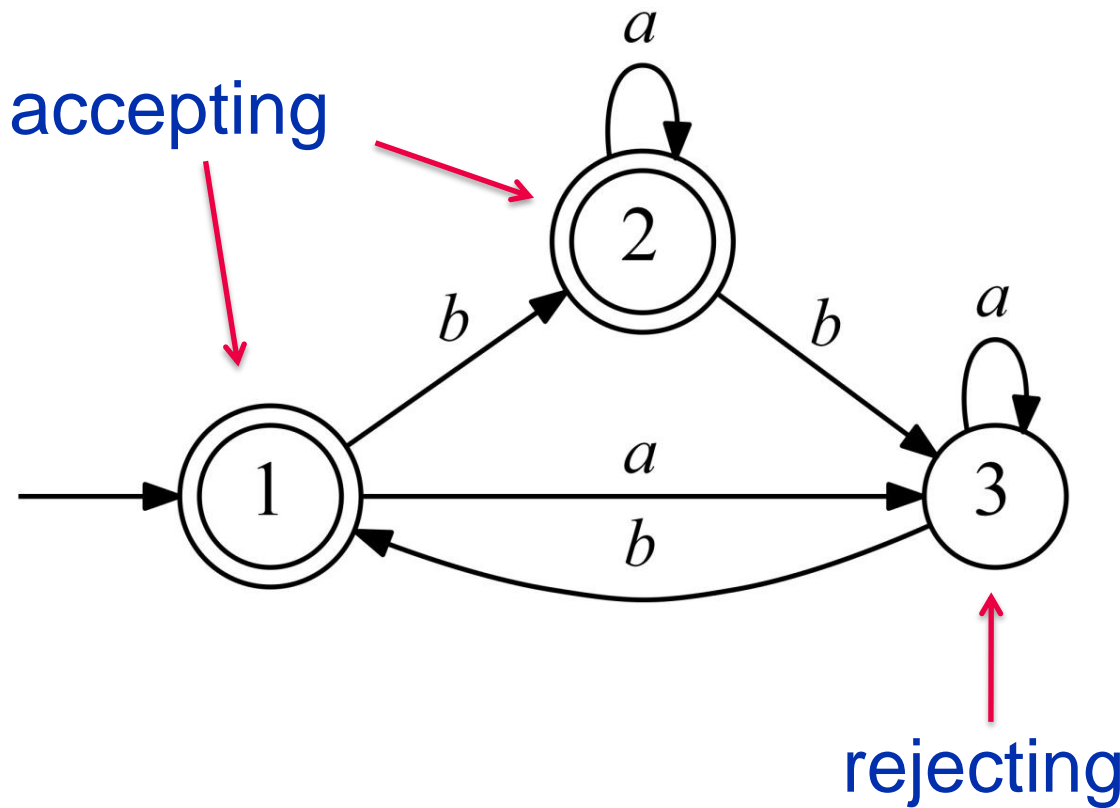


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Outline

- ✓ Introduction
- ✓ DFASAT algorithm overview
- ✓ Handling noise in DFASAT
- ✓ BFS-based symmetry breaking for DFASAT
- ✓ Experiments
- ✓ Conclusions

Deterministic Finite Automata (DFA)

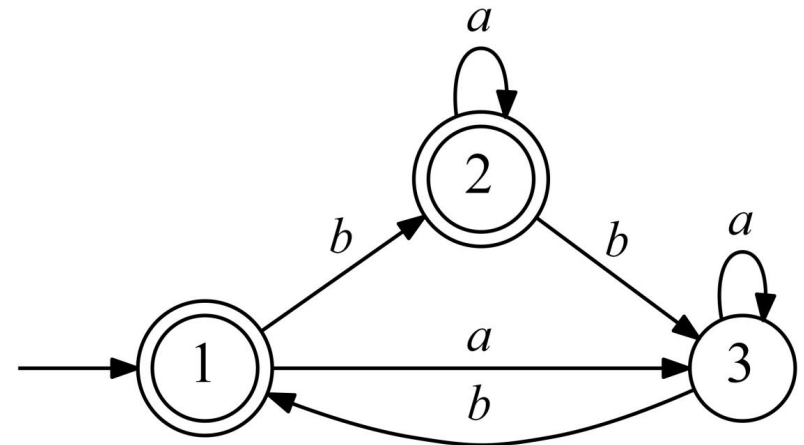
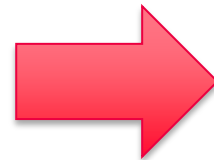


- ✓ S_+
 - ab
 - b
 - ba
 - bbb
- ✓ S_-
 - abbb
 - baba

DFA Identification Problem

$S_+ = \{ab, b, ba, bbb\}$

$S_- = \{abbb, baba\}$



- ✓ Identifying a **minimal** DFA is NP-hard [Gold, 1978]

DFA Identification From Noisy Data

- ✓ K string labels are randomly flipped

$S_+ = \{ab, b, ba, \text{bbb}\};$ $S_- = \{abbb, baba\}$

$S_+ = \{ab, b, ba\};$ $S_- = \{abbb, baba, \text{bbb}\}$



Previous Research

- ✓ Evolutionary algorithm with smart state labeling [Lucas et al., 2005]
 - State of the art for noisy case
- ✓ **DFASAT [Heule & Verwer, 2010]**
 - **State of the art for noiseless case**

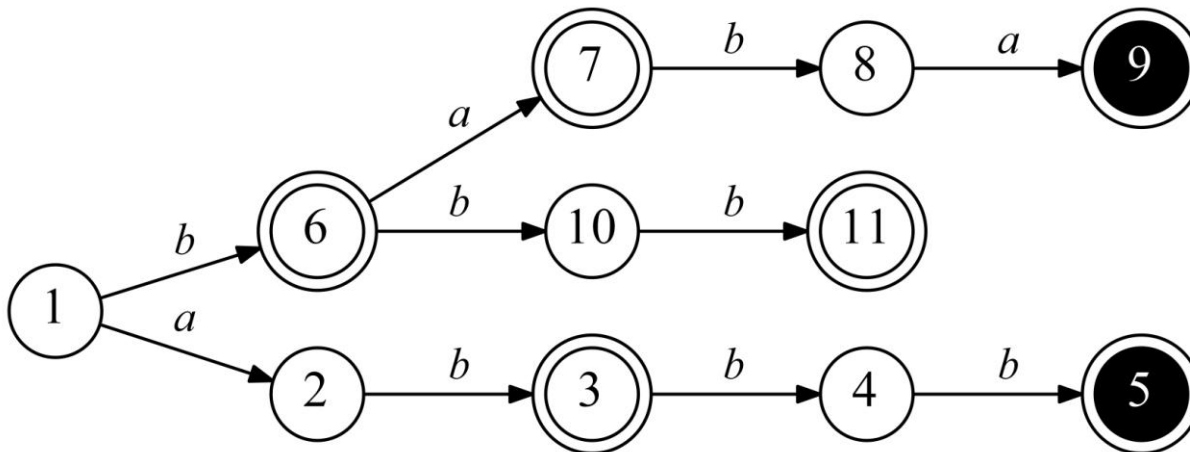
Our contribution

- ✓ We focus on DFASAT
- ✓ Augment DFASAT to handle **noisy data**
- ✓ Augment DFASAT with **new symmetry breaking predicates**

DFASAT [Heule & Verwer, 2010]

1. Augmented Prefix Tree Acceptor construction
2. Consistency Graph construction
3. CNF Boolean Formula construction
4. SAT-solver execution
5. DFA reconstruction from satisfying assignment

Augmented Prefix Tree Acceptor



✓ S_+

✓ S_-

- ab

- abbb

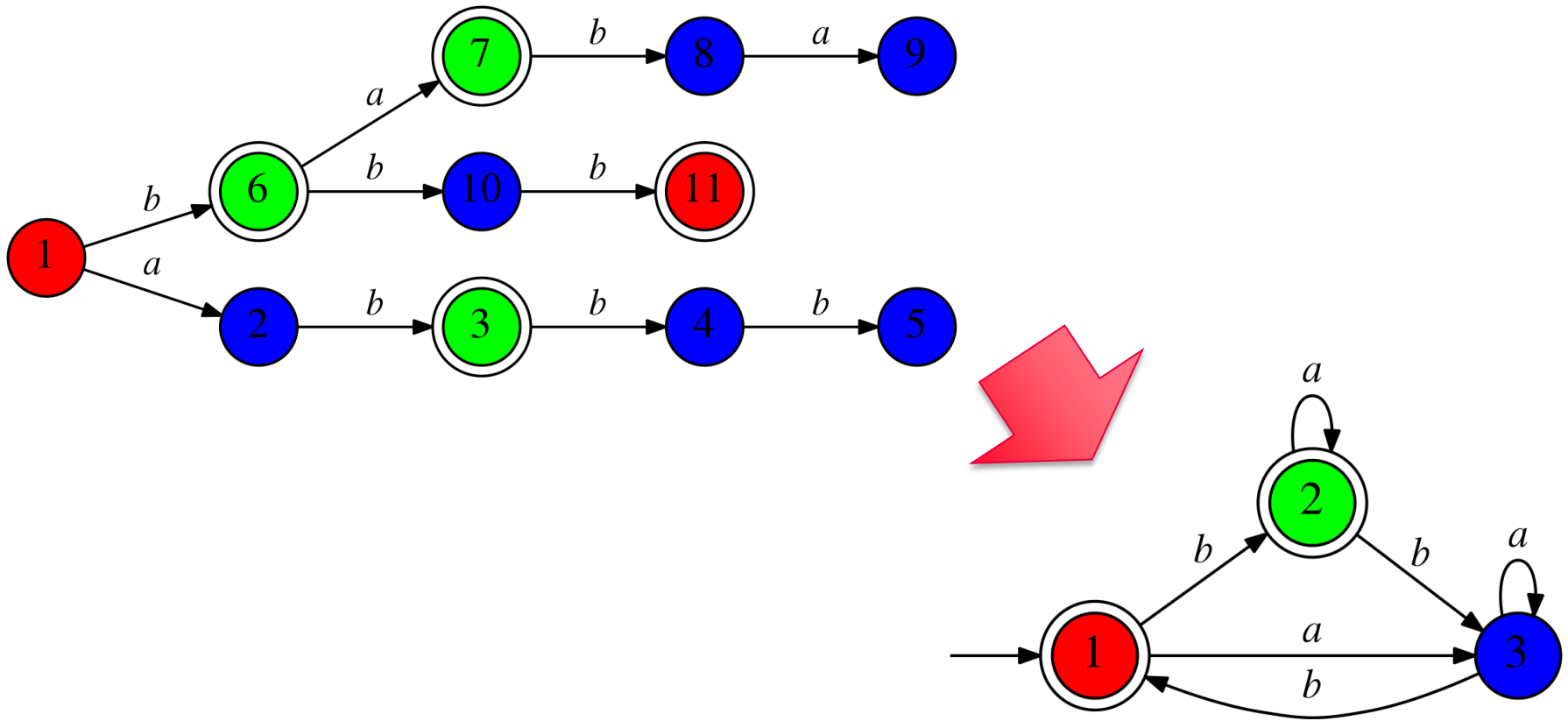
- b

- baba

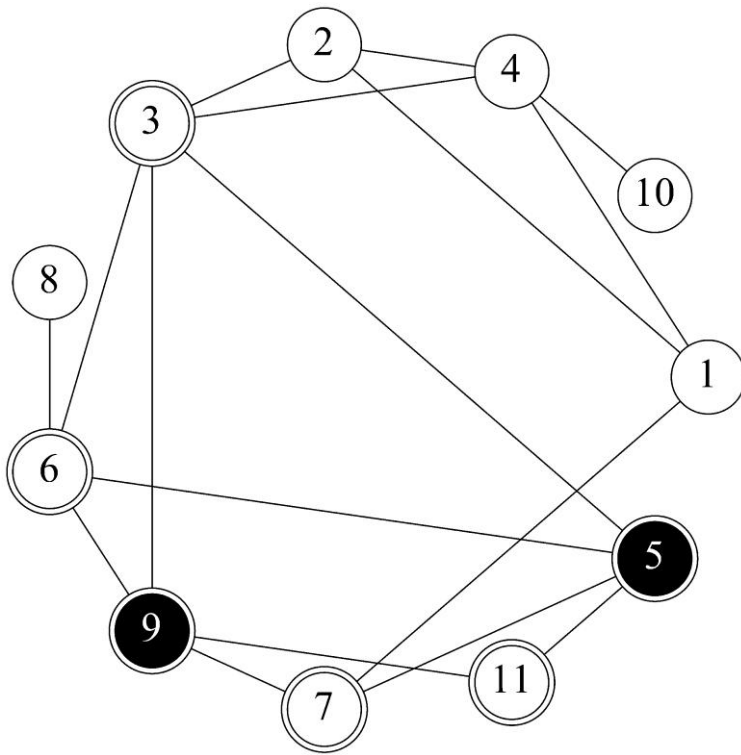
- ba

- bbb

Main idea: APTA coloring



Consistency Graph



- ✓ Nodes – same as APTA states
- ✓ Two nodes are connected if they cannot be merged into one DFA state
- ✓ Only exists in the noiseless case

Variables

- ✓ **Color variables** $x_{v,i} \equiv 1$ iff APTA state v has color i
- ✓ **Parent relation variables** $y_{l,i,j} \equiv 1$ iff DFA transition with symbol l from state i ends in state j
- ✓ **Accepting color variables** $z_i \equiv 1$ iff DFA state i is accepting

Types of clauses (1)

V_+ – accepting states
 V_- – rejecting states

✓ **Accepting states colors**

$$x_{v,i} \Rightarrow z_i, v \in V_+$$

✓ **Rejecting states colors**

$$x_{v,i} \Rightarrow \neg z_i, v \in V_-$$

✓ **Each state has at least one color**

$$x_{v,1} \vee x_{v,2} \vee \dots \vee x_{v,C}$$

✓ **Each state has at most one color**

$$\neg x_{v,i} \vee \neg x_{v,j}, i < j$$

Types of clauses (2)

$p(v)$ – parent of APTA state v
 $l(v)$ – incoming symbol of APTA state v

- ✓ A DFA transition is set when a state and its parent are colored

$$x_{p(v),i} \wedge x_{v,j} \Rightarrow y_{l(v),i,j}$$

- ✓ Each DFA transition must target **at least** one state

$$y_{l,i,1} \vee y_{l,i,2} \vee \dots \vee y_{l,i,C}$$

- ✓ Each DFA transition can target **at most** one state

$$y_{l,i,j} \Rightarrow \neg y_{l,i,k}, j < k$$

Types of clauses (3)

- ✓ State color is set when DFA transition and parent color are set

$$y_{l(v),i,j} \wedge x_{p(v),i} \Rightarrow x_{v,j}$$

- ✓ Colors of two states connected with an edge in the consistency graph must be different

$$x_{v,i} \Rightarrow \neg x_{w,i}, (v, w) \in E$$

Noisy DFA Identification

✓ K random attribution labels are *flipped*

$S_+ = \{ab, b, ba, \mathbf{bbb}\}; \quad S_- = \{abbb, baba\}$

$S_+ = \{ab, b, ba\}; \quad S_- = \{abbb, baba, \mathbf{bbb}\}$



Noisy DFA Identification: Issues

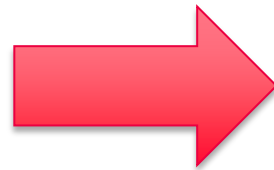
- ✓ Consistency graph is undefined
- ✓ We do not know the exact labels of strings
- ✓ How can we modify the described translation to deal with noise?

Noisy DFA Identification (2)

- ✓ New variables f_v
- ✓ $f_v \equiv 1$ iff the label of state v can (but does not have to) be incorrect (flipped)
- ✓ Modify clauses for state colors

$$x_{v,i} \Rightarrow z_i, v \in V_+$$

$$x_{v,i} \Rightarrow \neg z_i, v \in V_-$$

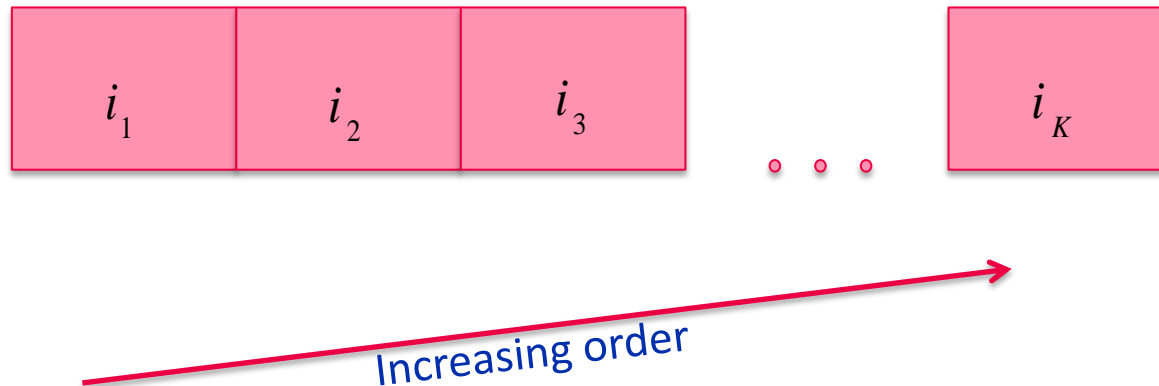


$$\neg f_v \Rightarrow (x_{v,i} \Rightarrow z_i), v \in V_+$$

$$\neg f_v \Rightarrow (x_{v,i} \Rightarrow \neg z_i), v \in V_-$$

Noisy DFA Identification (3)

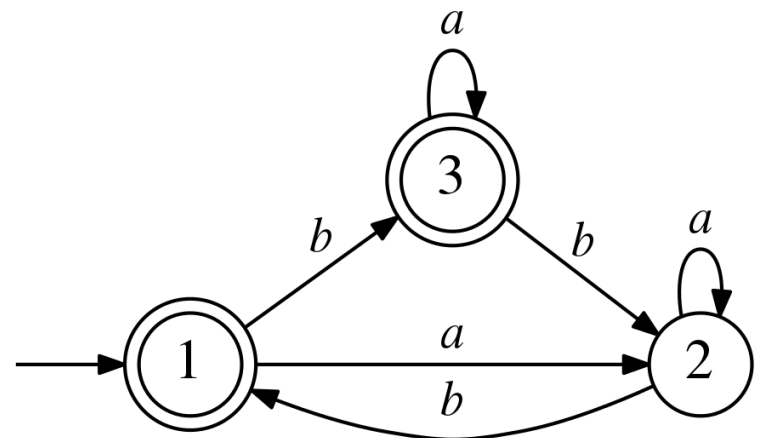
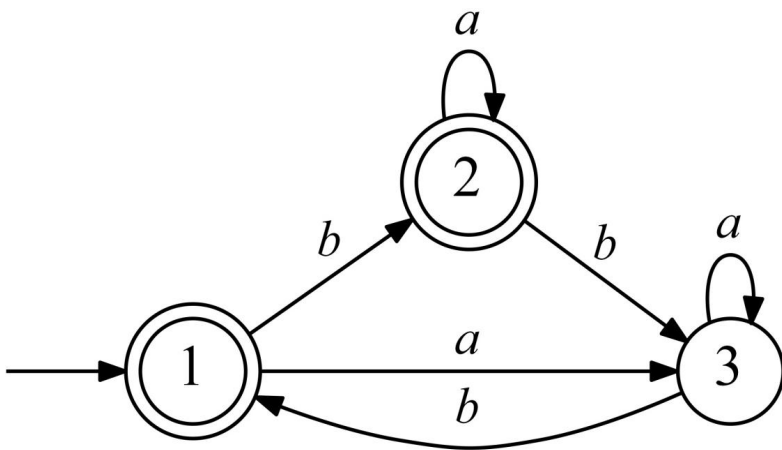
- ✓ Array of length K
- ✓ Numbers of APTA states for which that can be flipped



- ✓ Some extra variables and clauses for representing that as a Boolean formula; *order encoding* method used

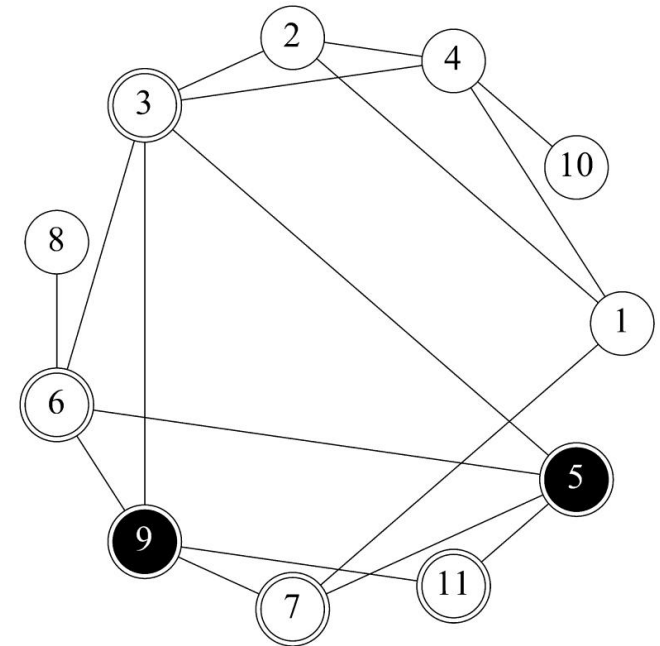
Symmetry breaking

- ✓ Many optimization problems exhibit symmetries
- ✓ Here: groups of isomorphic DFA

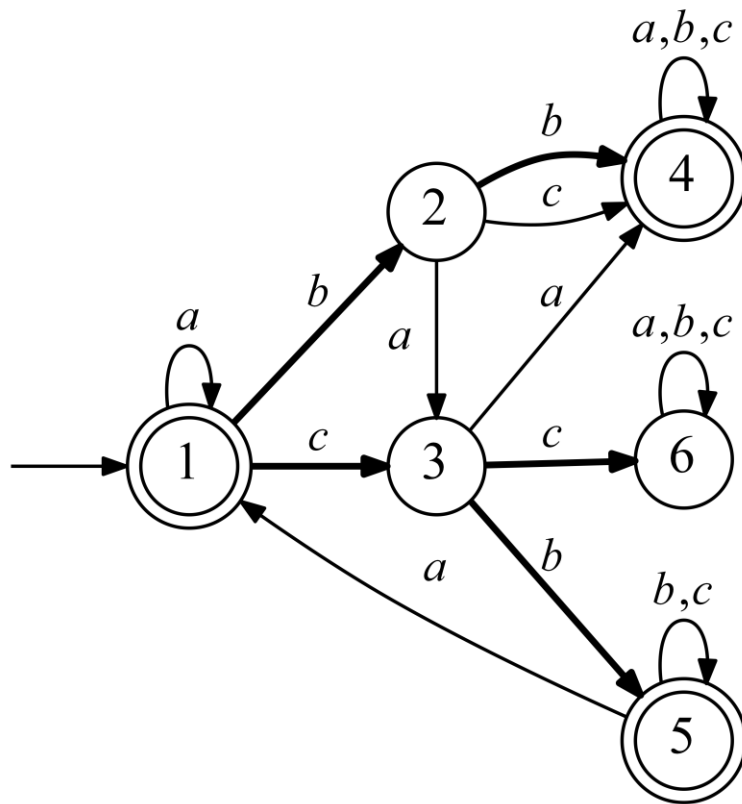


Max-clique symmetry breaking [Heule & Verwer, 2010]

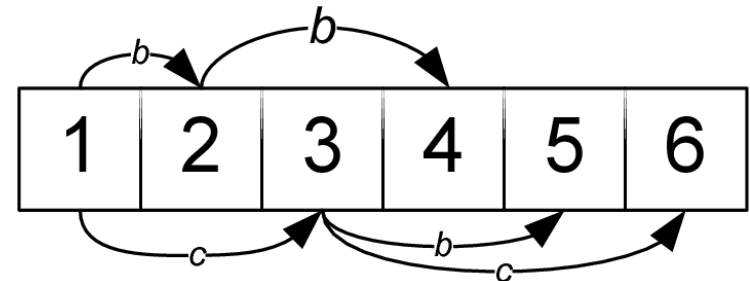
- ✓ Find a big clique in the CG with fast heuristic algorithm
- ✓ Fix colors of clique states in the APTA
- ✓ Note: not applicable in the noisy case



BFS-based Symmetry Breaking Predicates



BFS-enumerated DFA



BFS queue

BFS-based Symmetry Breaking Predicates

- ✓ Idea – force the DFA to be BFS-enumerated
- ✓ Already used in several algorithms

- ✓ How do we encode BFS-enumeration in SAT?

Additional variables

- ✓ **Parents** variables $p_{j,i} \equiv 1$ iff state i is the parent of state j in the BFS-tree
- ✓ **Transition** variables $t_{j,i} \equiv 1$ iff there is a transition between states i and j

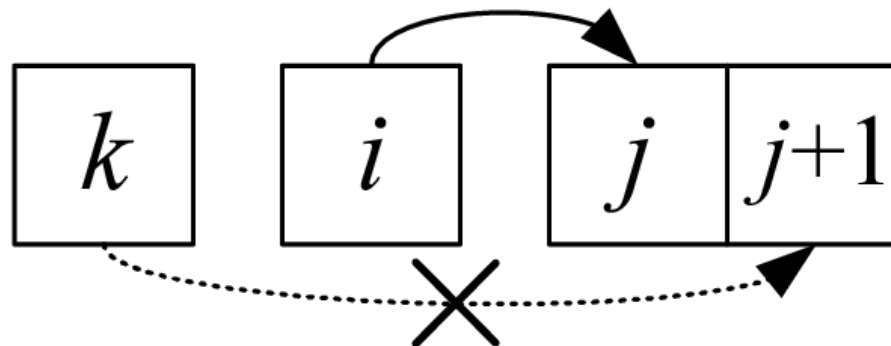
Ordering parents

- ✓ Each state except initial one must have a **parent** with a smaller number

$$p_{j,1} \vee p_{j,2} \vee \dots \vee p_{j,j-1}, 2 \leq j \leq C$$

- ✓ In BFS-enumeration states' **parents** must be ordered

$$p_{j,i} \Rightarrow \neg p_{j+1,k}, 1 \leq k < i < j < C$$



Ordering children

- ✓ Transition variables: there is a transition between states i and j

$$t_{i,j} \Leftrightarrow y_{l_1,i,j} \vee \dots \vee y_{l_L,i,j}, i < j$$

- ✓ State j was enqueued while processing the state with minimal number i among states that have a **transition** to j

$$p_{j,i} \Leftrightarrow (t_{i,j} \wedge \neg t_{i-1,j} \wedge \dots \wedge \neg t_{1,j}), i < j$$

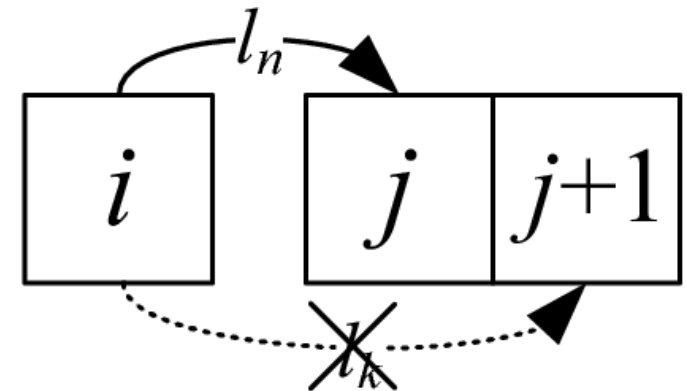
Ordering transitions

✓ Minimal symbol variables

$$m_{l_n, i, j} \Leftrightarrow y_{l_n, i, j} \wedge \neg y_{l_{n-1}, i, j} \wedge \dots \wedge \neg y_{l_1, i, j}, \quad i < j$$

✓ Arranging consecutive states j and $j+1$ with the same **parent** i in the alphabetical order of **minimal symbols** on **transitions** between them and i

$$p_{j, i} \wedge p_{j+1, i} \wedge m_{l_n, i, j} \Rightarrow \neg m_{l_k, i, j+1}, \quad i < j, \quad k < n$$



Experimental setup

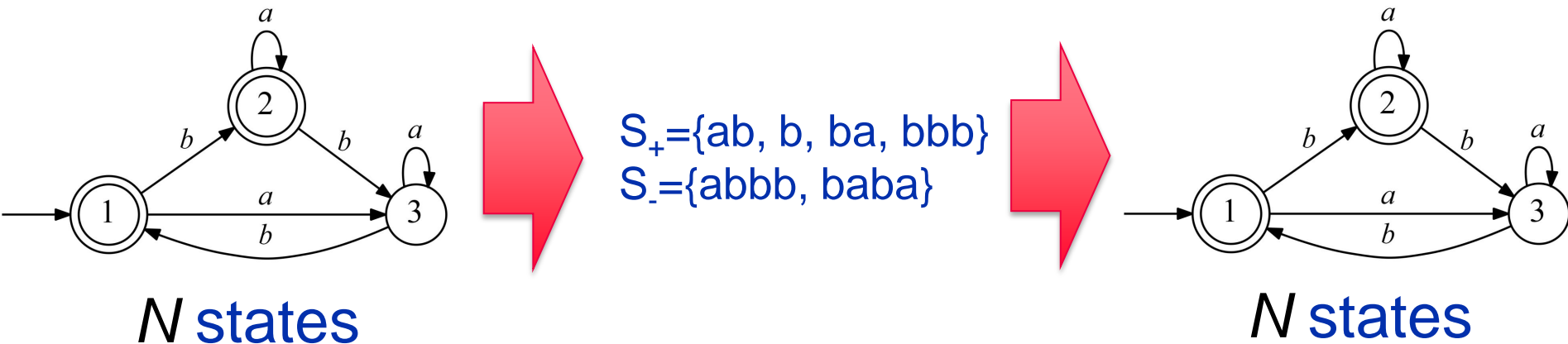
- ✓ Random data sets
- ✓ Binary alphabet
- ✓ TL – time limit ($TL = 1800$ seconds)
- ✓ *lingeling* SAT-solver
- ✓ Mean time among 100 launches of experiments

Noiseless DFA Identification

- ✓ DFASAT with max-clique symmetry breaking clearly outperforms our method

Noisy DFA Identification when target DFA exists

- ✓ N – size of the DFA used for generating input set of strings
- ✓ N – size of the target DFA



Noisy DFA Identification, $S = 10N$ strings

Number of states	Noise level, %	BFS, s	DFASAT, s	EA, s
5	2	0.22	0.38	1.22
5	4	0.59	0.9	1.1
6	2	1.05	2.44	2.94
6	4	3.34	7.82	2.85
7	1	4.34	10.83	21.36
7	3	17.22	143.66	19.16
8	1	17.89	31.58	30.29
8	2	163.92	225.31	19.8

Noisy DFA Identification, $S = 25N$ strings

Number of states	Noise level, %	BFS, s	DFASAT, s	EA, s
5	1	0.54	0.64	2.77
5	2	2.42	4.33	1.80
6	1	6.3	11.95	11.65
6	2	13.3	43.54	4.8
7	1	31.01	114.95	17.24
7	2	286.76	TL	13.11
8	1	239.46	404.32	21.73

Noisy DFA Identification, $S = 50N$ strings

Number of states	Noise level, %	BFS, s	DFASAT, sec	EA, s
5	1	4.2	7.59	6.07
5	2	12.87	22.36	3.05
6	1	20.76	52.5	20.39
6	2	107.94	309.22	11.28

Noisy DFA identification when the target DFA does not exist

- ✓ $(N + 1)$ – size of the DFA used for generating input set of strings
- ✓ N – size of the target DFA
- ✓ Note: the state-of-the-art EA cannot determine that a DFA consistent with a given set of strings **does not exist**

Noisy DFA identification when the target DFA does not exist, $S = 50N$ strings

N	K	BFS, s	DFASAT, s	Passed BFS, %	Passed DFASAT, %
5	1	11.57	257.13	100	100
5	2	46.42	1296.71	100	30
6	1	110.05	TL	100	0
6	2	581.73	TL	100	0
7	1	995.27	TL	89	0
7	2	TL	TL	0	0

Conclusion

- ✓ Exact solution for noisy DFA identification
- ✓ New symmetry breaking predicates based on BFS
 - Applicable in the noisy case
 - Greatly speed up the discovery of non-existence of a DFA
- ✓ Implementation
 - <http://github.com/ctlab/DFA-Inductor>

Acknowledgements

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Thank you for your attention!

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